NAG Fortran Library Routine Document G02DEF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

G02DEF adds a new independent variable to a general linear regression model.

2 Specification

SUBROUTINE GO2DEF(WEIGHT, N, IP, Q, LDQ, P, WT, X, RSS, TOL, IFAIL)
INTEGER

N, IP, LDQ, IFAIL

Q(LDQ,IP+2), P(IP+1), WT(*), X(N), RSS, TOL

CHARACTER*1

WEIGHT

3 Description

A linear regression model may be built up by adding new independent variables to an existing model. G02DEF updates the QR decomposition used in the computation of the linear regression model. The QR decomposition may come from G02DAF or a previous call to G02DEF. The general linear regression model is defined by

$$y = X\beta + \epsilon$$
,

where y is a vector of n observations on the dependent variable,

X is an n by p matrix of the independent variables of column rank k,

 β is a vector of length p of unknown parameters,

and ϵ is a vector of length n of unknown random errors such that $var \epsilon = V\sigma^2$, where V is a known diagonal matrix.

If V = I, the identity matrix, then least-squares estimation is used. If $V \neq I$, then for a given weight matrix $W \propto V^{-1}$, weighted least-squares estimation is used.

The least-squares estimates, $\hat{\beta}$ of the parameters β minimize $(y - X\beta)^T (y - X\beta)$ while the weighted least-squares estimates, minimize $(y - X\beta)^T W (y - X\beta)$.

The parameter estimates may be found by computing a QR decomposition of X (or $W^{\frac{1}{2}}X$ in the weighted case), i.e.,

$$X = QR^*$$
 (or $W^{\frac{1}{2}}X = QR^*$),

where $R^* = \begin{pmatrix} R \\ 0 \end{pmatrix}$ and R is a p by p upper triangular matrix and Q is an n by n orthogonal matrix.

If R is of full rank, then $\hat{\beta}$ is the solution to

$$R\hat{\beta} = c_1,$$

where $c = Q^T y$ (or $Q^T W^{\frac{1}{2}} y$) and c_1 is the first p elements of c.

If R is not of full rank a solution is obtained by means of a singular value decomposition (SVD) of R. To add a new independent variable, x_{p+1} , R and c have to be updated. The matrix Q_{p+1} is found such that $Q_{p+1}^T[R:Q^Tx_{p+1}]$ (or $Q_{p+1}^T[R:Q^TW^{\frac{1}{2}}x_{p+1}]$) is upper triangular. The vector c is then updated by multiplying by Q_{p+1}^T .

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The new independent variable is tested to see if it is linearly related to the existing independent variables by checking that at least one of the values $(Q^T x_{p+1})_i$, for $i = p+2, p+3, \ldots, n$, is non-zero.

The new parameter estimates, $\hat{\beta}$, can then be obtained by a call to G02DDF.

The routine can be used with p = 0, in which case R and c are initialised.

4 References

Draper N R and Smith H (1985) Applied Regression Analysis (2nd Edition) Wiley

Golub G H and van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

Hammarling S (1985) The singular value decomposition in multivariate statistics SIGNUM Newsl. **20 (3)** 2–25

McCullagh P and Nelder J A (1983) Generalized Linear Models Chapman and Hall

Searle S R (1971) Linear Models Wiley

5 Parameters

1: WEIGHT – CHARACTER*1

Input

On entry: indicates if weights are to be used.

If WEIGHT = 'U' (Unweighted), least-squares estimation is used.

If WEIGHT = 'W' (Weighted), weighted least-squares is used and weights must be supplied in the array WT.

Constraint: WEIGHT = 'U' or 'W'.

2: N - INTEGER

Input

On entry: the number of observations, n.

Constraint: N > 1.

3: IP – INTEGER

Input

On entry: the number of independent variables already in the model, p.

Constraint: $IP \ge 0$ and IP < N.

4: Q(LDQ,IP+2) - real array

Input/Output

On entry: if IP \neq 0, then Q must contain the results of the QR decomposition for the model with p parameters as returned by G02DAF or a previous call to G02DEF.

If IP = 0, then the first column of Q should contain the n values of the dependent variable, y.

On exit: the results of the QR decomposition for the model with p+1 parameters:

the first column of Q contains the updated value of c;

the columns 2 to IP + 1 are unchanged;

the first IP + 1 elements of column IP + 2 contain the new column of R, while the remaining N - IP - 1 elements contain details of the matrix Q_{n+1} .

5: LDQ – INTEGER

Input

On entry: the first dimension of the array Q as declared in the (sub)program from which G02DEF is called.

Constraint: LDQ \geq N.

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6: P(IP+1) - real array

Input/Output

On entry: P contains further details of the QR decomposition used. The first IP elements of P must contain the zeta values for the QR decomposition (see F08AEF (SGEQRF/DGEQRF) for details).

The first IP elements of array P are provided by G02DAF or by previous calls to G02DEF.

On exit: the first IP elements of P are unchanged and the (IP + 1)th element contains the zeta value for Q_{n+1} .

7: WT(*) - real array

Input

On entry: if WEIGHT = 'W', then WT must contain the weights to be used in the weighted regression.

If WT(i) = 0.0, then the *i*th observation is not included in the model, in which case the effective number of observations is the number of observations with non-zero weights.

If WEIGHT = 'U', then WT is not referenced and the effective number of observations is n.

Constraint: if WEIGHT = 'W', WT(i) ≥ 0.0 , for i = 1, 2, ..., n.

8: X(N) - real array

Input

On entry: the new independent variable, x.

9: RSS – **real** Output

On exit: the residual sum of squares for the new fitted model.

Note: this will only be valid if the model is of full rank, see Section 8.

10: TOL – real Input

On entry: the value of TOL is used to decide if the new independent variable is linearly related to independent variables already included in the model. If the new variable is linearly related then c is not updated. The smaller the value of TOL the stricter the criterion for deciding if there is a linear relationship.

Suggested value: TOL = 0.000001.

Constraint: TOL > 0.0.

11: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, because for this routine the values of the output parameters may be useful even if IFAIL $\neq 0$ on exit, the recommended value is -1. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

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```
IFAIL = 1 On entry, N < 1, or IP < 0, or IP \geq N, or LDQ < N, or TOL \leq 0.0, or WEIGHT \neq 'U' or 'W'. IFAIL = 2 On entry, WEIGHT = 'W' and a value of WT < 0.0. IFAIL = 3
```

The new independent variable is a linear combination of existing variables. The (IP + 1)th column of Q will therefore be null.

7 Accuracy

The accuracy is closely related to the accuracy of F08AGF (SORMQR/DORMQR) which should be consulted for further details.

8 Further Comments

It should be noted that the residual sum of squares produced by G02DEF may not be correct if the model to which the new independent variable is added is not of full rank. In such a case G02DDF should be used to calculate the residual sum of squares.

9 Example

A data set consisting of 12 observations is read in. The four independent variables are stored in the array X while the dependent variable is read into the first column of Q. If the character variable MEAN indicates that a mean should be included in the model a variable taking the value 1.0 for all observations is set up and fitted. Subsequently, one variable at a time is selected to enter the model as indicated by the input value of INDX. After the variable has been added the parameter estimates are calculated by G02DDF and the results printed. This is repeated until the input value of INDX is 0.

9.1 Program Text

Note: the listing of the example program presented below uses **bold italicised** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
GO2DEF Example Program Text
Mark 14 Release. NAG Copyright 1989.
.. Parameters ..
                 MMAX, NMAX
INTEGER
PARAMETER
                 (MMAX=5,NMAX=12)
INTEGER
                 NIN, NOUT
PARAMETER
                 (NIN=5, NOUT=6)
.. Local Scalars .
real
                 RSS, RSST, TOL
INTEGER
                 I, IDF, IFAIL, INDX, IP, IRANK, J, M, N
LOGICAL
                 SVD
CHARACTER
                 MEAN, WEIGHT
.. Local Arravs ..
real
                 B(MMAX), COV(MMAX*(MMAX+1)/2), P(MMAX*(MMAX+2)),
                 Q(NMAX,MMAX+1), SE(MMAX), WK(MMAX*MMAX+5*MMAX),
                 WT(NMAX), X(NMAX,MMAX)
.. External Subroutines .
                 FO6FBF, GO2DDF, GO2DEF
EXTERNAL
.. Executable Statements ..
WRITE (NOUT,*) 'GO2DEF Example Program Results'
```

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```
Skip heading in data file
      READ (NIN, *)
      READ (NIN,*) N, M, WEIGHT, MEAN
      IF (N.LE.NMAX .AND. M.LT.MMAX) THEN
         IF (WEIGHT.EQ.'W' .OR. WEIGHT.EQ.'w') THEN
            DO 20 I = 1, N
               READ (NIN,*) (X(I,J),J=1,M), Q(I,1), WT(I)
   20
            CONTINUE
         ELSE
            DO 40 I = 1. N
               READ (NIN, \star) (X(I,J),J=1,M), Q(I,1)
   40
            CONTINUE
         END IF
         Set tolerance
         TOL = 0.000001e0
         IP = 0
         IF (MEAN.EQ.'M' .OR. MEAN.EQ.'m') THEN
            CALL F06FBF(N, 1.0e0, X(1, MMAX), 1)
            IFAIL = 0
            CALL GO2DEF(WEIGHT, N, IP, Q, NMAX, P, WT, X(1, MMAX), RSS, TOL, IFAIL)
            TP = 1
         END IF
         READ (5,*) INDX
   60
         IF (INDX.GT.O) THEN
            IFAIL = -1
            CALL GO2DEF(WEIGHT, N, IP, Q, NMAX, P, WT, X(1, INDX), RSS, TOL, IFAIL)
            IF (IFAIL.EQ.O) THEN
                IP = IP + 1
                WRITE (NOUT, *)
               WRITE (NOUT, 99999) 'Variable', INDX, ' added'
               RSST = 0.0e0
                IFAIL = 0
                CALL GO2DDF(N, IP, Q, NMAX, RSST, IDF, B, SE, COV, SVD, IRANK, P,
                            TOL, WK, IFAIL)
                IF (SVD) THEN
                   WRITE (NOUT, *) 'Model not of full rank'
                   WRITE (NOUT, *)
               END IF
                WRITE (NOUT,99998) 'Residual sum of squares = ', RSST
               WRITE (NOUT, 99999) 'Degrees of freedom = ', IDF
               WRITE (NOUT, *)
               WRITE (NOUT, *)
                  'Variable
                              Parameter estimate
                                                   Standard error'
                WRITE (NOUT, *)
                DO 80 J = 1, IP
                   WRITE (NOUT,99997) J, B(J), SE(J)
   80
                CONTINUE
            ELSE IF (IFAIL.EQ.3) THEN
               WRITE (NOUT, *) ' * New variable not added *'
            ELSE
               GO TO 100
            END IF
            GO TO 60
         END IF
      END IF
  100 CONTINUE
      STOP
99999 FORMAT (1X,A,I4,A)
99998 FORMAT (1X,A,e13.4)
99997 FORMAT (1X,16,2e20.4)
      END
```

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9.2 Program Data

```
GO2DEF Example Program Data 12 4 'U' 'M'
1.0 1.4 0.0 0.0 4.32
1.5 2.2 0.0 0.0 5.21
2.0 4.5 0.0 0.0 6.49
2.5 6.1 0.0 0.0 7.10
3.0 7.1 0.0 0.0 7.94
3.5 7.7 0.0 0.0 8.53
4.0 8.3 1.0 4.0 8.84
4.5 8.6 1.0 4.5 9.02
5.0 8.8 1.0 5.0 9.27
5.5 9.0 1.0 5.5 9.43
6.0 9.3 1.0 6.0 9.68
6.5 9.2 1.0 6.5 9.83
3
4
2
0
```

9.3

```
Program Results
GO2DEF Example Program Results
Variable 1 added
Residual sum of squares =
                         0.4016E+01
Degrees of freedom = 10
Variable Parameter estimate Standard error
              0.4410E+01
                                  0.4376E+00
    1
    2
              0.9498E+00
                                  0.1060E+00
Variable 3 added
                         0.3887E+01
Residual sum of squares =
Degrees of freedom = 9
Variable Parameter estimate Standard error
              0.4224E+01
                                 0.5673E+00
              0.1055E+01
    2
                                  0.222E+00
              -0.4196E+00
    3
                                 0.7670E+00
Variable 4 added
Residual sum of squares = 0.1870E+00
Degrees of freedom = 8
Variable Parameter estimate Standard error
    1
              0.2760E+01
                                  0.1759E+00
    2
              0.1706E+01
                                 0.7310E-01
    3
              0.4458E+01
                                 0.4268E+00
    4
              -0.1301E+01
                                 0.1034E+00
Variable 2 added
Residual sum of squares = 0.8407E-01
Degrees of freedom = 7
Variable Parameter estimate Standard error
    1
              0.3144E+01
                                 0.1818E+00
                                 0.2776E+00
    2
              0.9075E+00
    3
              0.2079E+01
                                 0.8680E+00
              -0.6159E+00
                                 0.2453E+00
    4
              0.2922E+00
                                 0.9981E-01
```

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